Returns to Scale and Structural Change

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Motivation

- Suppose returns to scale evolves over time, increasing
- What are the implications for economic growth ?
- What are the implications for structural change?



Two past streams of literature

RTS and economic growth

Solow (1956), Diamond (1965)

DRTS \rightarrow convergence steady state

CRS → steady state only at origin, all trajectories conv to balan ced growth paths

- □ Solow (1997) ~ CRS unlikely
- Endog growth lit

IRTS → stable, interior steady states with unbounded growth or decline leading to poverty traps



Two past streams of literature

RTS & Industrial Structure

Baumol (1983, 1988) IRTS and structure when markets are contestable

- Winter et al. (2006) Heterogeneous firms, continuous stochastic entry
- Loyland and Ringstad (2001) structural effects of scaleaugmenting tech change for Norwegian dairy industry estimate # farms would be reduced by 85% in absence of policy



Key Results from Lit



Questions and this paper

Questions

- How does RTS affect the structure of a network of interdependent enterpr ises?
- How does network structure affect growth?

This paper

- Dynamic simulation approach to structural change
 - Resource use change over time
 - Consideration of interdependence across multiple enterprises
 - Consideration of environmental processes, e.g. pollution
 - Illustration of the role of RTS in above

Approach

- Consider of small network of interdependent enterprises
- Numerical simulation under varying RTS cases

Interdependence

Interdependence

- Intermediacy of goods produced (vertical)
- Externality production (horizontal, vertical, spatial)
- Joint dependence on common resources
- Differential interest in network member and network performance.
- Complexity
 - Discrete and continuous time dynamic processes
- Dynamics
 - Process dynamics
 - Investment
 - Adjustment costs



Approach

Sylized multiple enterprise growth model

Interpretation

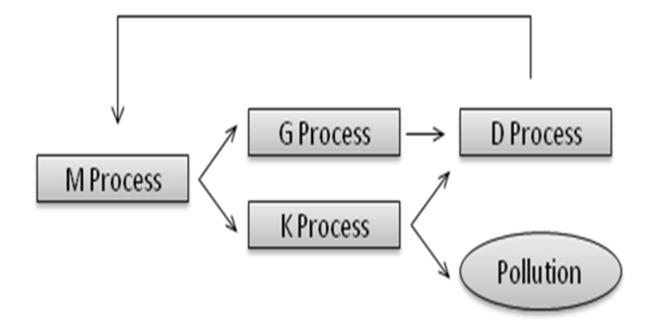
Multi-shop supply network feeding OEM

Dairy farm with integrated dairy, field crop, and pasture enterprises

Numerical computational solutions & simulation



Small network process architecture





Field of operations

Suppose there are multiple "shops" (a.k.a. fields)

- Suppose each shop specializes in one of a vector of outputs (crops)
- Shops supply an OEM (dairy)
- OEM produces intermediate good for shops (manure) that is a potential source of pollution
- Shops purchase inputs and use OEM's intermediate good to augment productivity (manure + fertilizer → nitrogen)
- But....use of those inputs yields pollution



Discrete time process (t clock) - a.k.a. crops

K Process *ith shop (field) ith product (crop)* $y_{k,i}^{j}(t) = A_{k,i}^{j}(t) \left(Z_{k,i}^{j}(t)\right)^{\alpha_{1}} \left(x_{m,i}^{j}(t)\right)^{\alpha_{2}} \theta_{k,i}^{j}(t)$

$$\dot{A}_{k,i}^{j}(t) = a_{0} x_{m,i}^{j}(t) A_{k,i}^{j}(t) - a_{y} y_{k,i}^{j}(t)$$

tech & controlled augmentation use based diminution

$$\dot{I}_{k,i}^{j}(t) = y_{k,i}^{j}(t) - s_{k,i}^{j}(t) - x_{k,i}^{j}(t)$$



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Characterizing RTS and dynamics

$$\phi(\lambda, t) = \lambda^{\alpha_1(t) + \alpha_2(t)}$$

$$\psi(t) = (\partial \phi(\lambda, t) / \partial \lambda)(\lambda / \phi(\lambda, t)) = \alpha_1(t) + \alpha_2(t)$$

$$\dot{\psi}(t) = v_1 \dot{\alpha}_1(t) + v_2 \dot{\alpha}_2(t)$$
 where $\dot{\alpha}_1(t) = \dot{\alpha}_2(t)$ and $v_q = \alpha_q / (\alpha_1 + \alpha_2)$

Thus, process output dynamics can be expressed in terms of RTS dynamics.



Continuous process enterprises (*d*=1,....*D*)

D Process (tau clock)

$$y_d(\tau) \equiv L_d, (\tau) Z_d^{\xi_1}(\tau) x_f^{\xi_2}(\tau)$$

 $\xi_1 + \xi_2 \le 1$

Vintage Function

$$L_{d}(\tau) \equiv \mu v_{d}^{\omega_{1}}(\tau) e^{\omega_{2} v_{d}}$$
$$v_{d}(\tau) = \tau - \tau_{d}$$



Joint output as a source of pollution

D Process

$$y_m(\tau) \equiv H * Z_m^{\beta_1}(\tau) * x_f^{\beta_2}(\tau), \ \beta_1 + \beta_2 \le 1$$

$$\dot{I}_{m}(\tau) = y_{m}(\tau) - s_{m}(\tau) - x_{m}(\tau)$$

 $x_{f}(\tau)$ is an input to M and D process which is written as

$$x_{f}(\tau) \equiv \lambda_{k} \sum_{i} x_{k,i}(t) + \lambda_{g} x_{g}(\tau) + \lambda_{c} x_{c}(\tau)$$



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Pollution

$$x_{m}(t) \equiv \sum_{i} \sum_{j} x_{m,i}^{j}(t)$$
$$x_{m}(t) \leq \sum_{m} I_{m}(t)$$

Potential pollution via intermediate flow from D process

$$y_{n,i}\left(\tau\right) \equiv n_{f}\left(x_{m}\left(t\right)+1\right)\left(x_{f}\left(\tau\right)+1\right)+n_{k}\left(\sum_{j}Z_{k,i}^{j}\left(t\right)\right)$$



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Applications : Pollution Control

Pollution as residual of potential – recycling (uptake)

$$e_{n,i}(\tau) \equiv y_{n,i}(\tau) - u_{k,i}(\tau), \quad i = 1, 2, ..., n$$

where $u_{k,i}(\tau)$ is the usage of by-products, which can be written as

$$\begin{split} u_{k,i}\left(\tau\right) &= u_{kk} \ast v_k\left(\tau\right) \ast \sum_j y_{k,i}^j\left(t\right) \\ v_k\left(\tau\right) &= 1/\tau^2 \end{split}$$



Continuous process by shops (grass)

$$y_g(\tau) = A_g(\tau) * (Z_g(\tau))^{\gamma_z} * (x_m(\tau))^{\gamma_x}$$

$$\dot{A}_{g}(\tau) = a_{g,0} x_{m}(\tau) A_{g}(\tau) - a_{g,y} y_{g}(\tau)$$

$$\dot{I}_{g}\left(\tau\right) = y_{g}\left(\tau\right) - s_{g}\left(\tau\right) - y_{c}\left(\tau\right)$$

Intermediate use based on processing (cutting)

$$y_{c}(\tau) \equiv \dot{I}_{c}(\tau) + s_{c}(\tau)$$



Network profits

$$\pi(\tau) = \sum_{t} \sum_{i} P_{k} s_{k,i}(t) + \int_{\tau_{0}}^{\tau_{f}} \sum_{m} P_{m} s_{m}(\tau) d\tau + \int_{\tau_{0}}^{\tau_{f}} \sum_{d} P_{d} s_{d}(\tau) d\tau \qquad \text{Revenue}$$

$$+ \int_{\tau_{0}}^{\tau_{f}} \sum_{c} P_{c} s_{c}(\tau) d\tau - \sum_{t} \sum_{k} R_{k} Z_{k}(t) - \int_{\tau_{0}}^{\tau_{f}} \sum_{m} R_{m} Z_{m}(\tau) d\tau \qquad \text{Input cost}$$

$$- \int_{\tau_{0}}^{\tau_{f}} \sum_{d} R_{d} Z_{d}(\tau) d\tau - \int_{\tau_{0}}^{\tau_{f}} \sum_{k} c_{k} I_{k}^{c_{1}}(\tau) d\tau - \int_{\tau_{0}}^{\tau_{f}} \sum_{m} c_{m} I_{m}^{c_{2}}(\tau) d\tau \qquad \text{Inventory cost}$$

$$- \int_{\tau_{0}}^{\tau_{f}} \sum_{n} c_{n} I_{n}(\tau) d\tau - \int_{\tau_{0}}^{\tau_{f}} \sum_{g} c_{c} I_{c}(\tau) d\tau - \int_{\tau_{0}}^{\tau_{f}} \sum_{i} k(b_{n,i}(\tau), e_{n}(\tau)) \qquad \text{Environmental cost}$$

$$- \int_{\tau_{0}}^{\tau_{f}} \sum_{i} c_{u} u_{k,i}(\tau) - \int_{\tau_{0}}^{\tau_{f}} \sum_{n} P_{n} e_{n}(\tau) d\tau$$



Control problem

$$w(\tau) \equiv w_1 \sum_{\tau} e_n(\tau) + w_2 \sum_{\tau} \left(e_n(\tau) \right)^2 + w_3 \sum_{\tau} \pi(\tau)$$

$$J = \max \int_{\tau_0}^{\tau_f} w(\tau) d\tau$$

Subject to dynamics of processes



Summary of notation

Table : Inputs and outputs of each process.

Process	Input	Output	Sell	Intermediate	Inventory
K	x_m, Z_k^j	\mathcal{Y}_k^j	s_k^j	x_k	I_k
М	x_f, Z_m	y_m	s _m	x_m	I_m
D	x_f, Z_d	\mathcal{Y}_d	N/A	N/A	N/A
N	x_f, x_m, Z_k^j	\mathcal{Y}_n	e_n^j (by-products)	N/A	I_n
G	x_m, Z_g	y_g, y_c	s _c	x_g, x_c	I_g, I_c



Parameterization

Prices, unit costs

Parameters	P_k	P_m	P_d	P_c	P_n	w_1	w2	W3	c1
Value	15	8	30	10	0/Varies ¹	0/-0.9 ¹	0/-0.2 ¹	1	0.7
Parameters	R_k	R_m	R_d	Rg	c_k	c _m	c _n	C _C	c_2
Value	10	3	5	7	0.5	2	0.9	2	0.19

Table 2: Parameters used in simulation



Parameterization

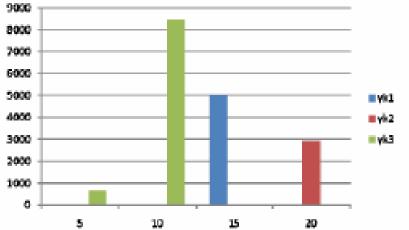
Process				
К	Batch (crops)	Alpha1=0.5	Alpha2=0.3	
Adot	Ш	a0 = 0.0001	a4=0.0004	
D	Continuous (milk)	eta1=0.5	etak1=0.29 etak2=0.07 etak3=0.01	
Ld	Vintage (lactation)	Mu=0.5	W1=0.68	W2=0.6
Μ	Potential poll (manure)	Beta1=0.5	Beta2=0.29	
Xf	Intermed (feed)	Lambdak=0.5	Lam g=0.25	Lam c=0.25
Yn	Pollutant	Nf=0.01	Nk=0.1	Cn=0.9
Yg	Continuous (grass)	Gamma z=0.5	Gamma x=0.3	
Ag dot	"	Ag0=0.00005	Agy=0.0003	

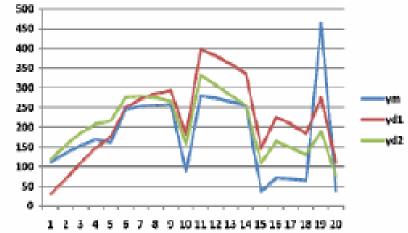
PENN<u>State</u>



CASE 1: Near Constant returns to scale, $\psi(t) = 0.99$. CASE 2: Decreasing returns to scale $\psi(t) = 0.80$, no abatement. CASE 3: Decreasing returns to scale $\psi(t) = 0.50$, no abatement.







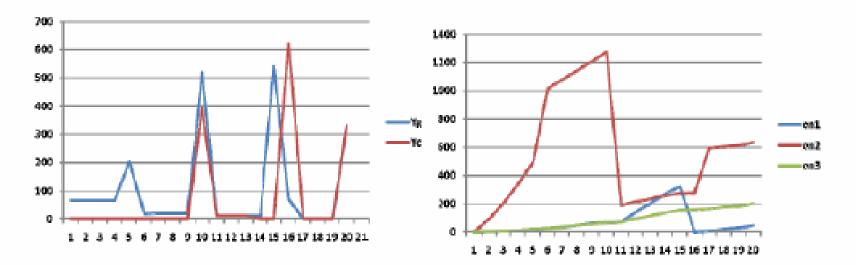


FIGURE 2. Case 1a. Output and Pollution Dynamics



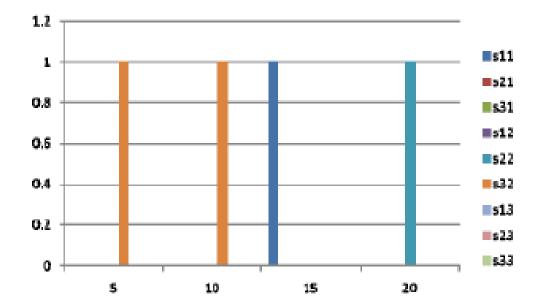
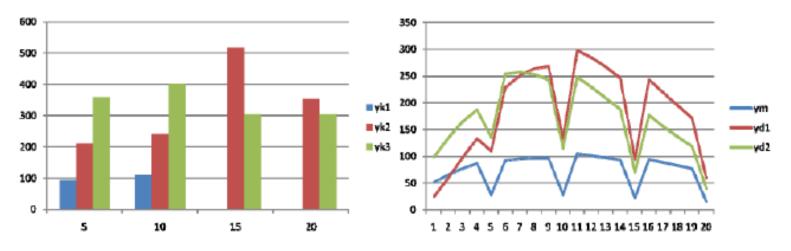


FIGURE 3. Case 1a Optimal scales of operation $\theta_{k,i}^{j}(t) = \text{sij} = \text{scale of } i^{th} \text{ product by } j^{th} \text{ shop.}$





DRTS → diversification, intensification

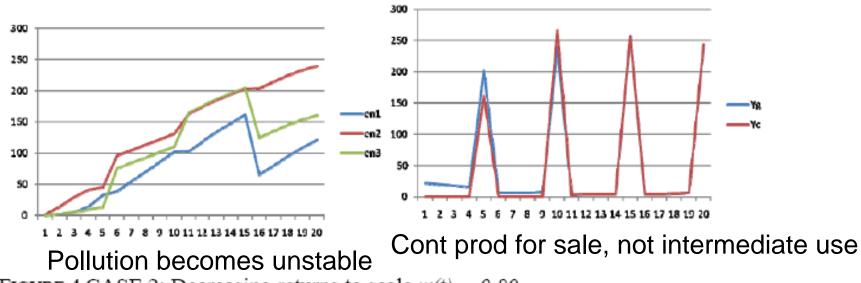


FIGURE 4 CASE 2: Decreasing returns to scale $\psi(t) = 0.80$.

PENNSTATE

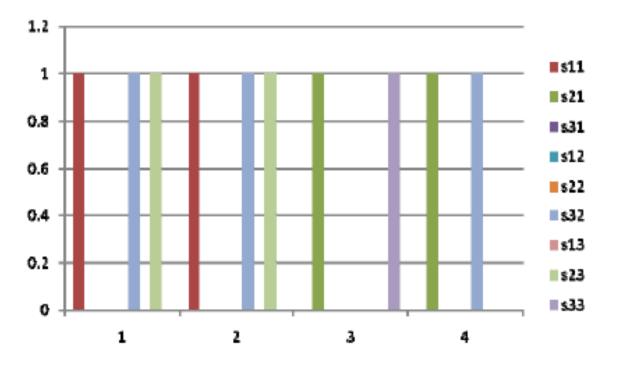


FIGURE 5 CASE 2: Decreasing returns to scale $\psi(t) = 0.80$. Optimal scales of operation $\theta_{k,i}^{j}(t) = \text{sij} = \text{scale of } i^{th} \text{ product by } j^{th} \text{ shop.}$



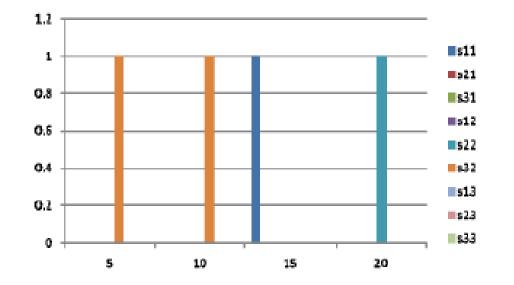
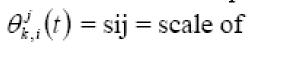


FIGURE 3. Case 1a Optimal scales of operation



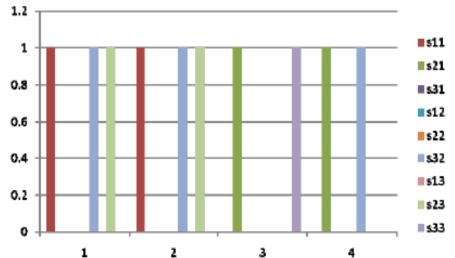


FIGURE 5 CASE 2: Decreasing returns to scale $\psi(t) = 0.80$. Optimal scales of operation $\theta_{k,i}^{j}(t) = \text{sij} = \text{scale of } i^{th} \text{ product by } j^{th} \text{ shop.}$



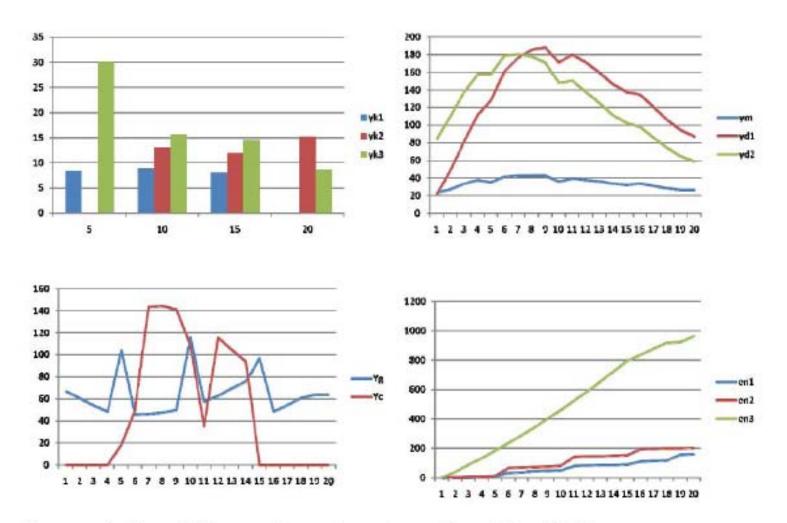


FIGURE 6 CASE 2 Decreasing returns to scale $\psi(t) = 0.50$.



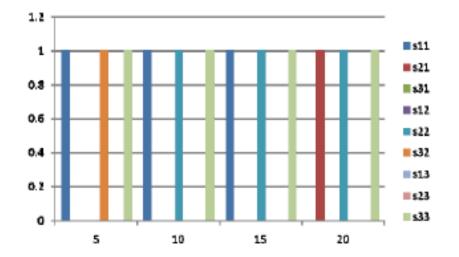


FIGURE 7 CASE 2 Decreasing returns to scale $\psi(t) = 0.50$. Optimal scales of operation $\theta_{k,i}^{j}(t) = \text{sij} = \text{scale of } i^{th} \text{ product by } j^{th} \text{ shop.}$



Structural Implications

- Resource use transition and dynamics is analyzed
- As RTS increases specialization increases

